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# **Brushless Vibrator Driver**

# Built-in Hall Sensor



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## Brushless Vibrator Driver Built-in Hall Sensor

#### **General Specifications**

The device is designed specifically for brushless DC motor applications without any external components, such as vibrator, ultra-small blushless motor. Each device includes a HALL sensor, a lock detection circuit to shut down the driver output for the lock prevention, and complementary bi-directional drivers for driving and sinking coil load.

If the motor rotation is stall by external forces or obstacles, the drivers will shut down roughly 0.5 to 2 seconds after the motor is locked. When the drivers shut down, the automatic self-restart circuit will try to power up the drivers every 0.5 to 2 seconds till the motor locking is released.

#### **Pin Description**

NO.	NAME	Description
1	O2	Output Driver2
2	NC	No Connection
3	VSS	Ground
4	01	Output Driver1
5	NC	No Connection
6	VDD	Power

#### **Features and Benefits**

- Optimized for small Brushless DC Motor applications
- Low voltage operation
- Built-in Hall effect sensor
- Built-in Reverse Protection
- Lock detection and automatic self-restart without external capacitor
- High sinking and driving output capability
- Thin, highly reliable package (CSP6)

Characteristic	Symbol	Rating	Unit
Supply Voltage	V <sub>DD</sub>	5.5	V
Output Current	I <sub>OUT</sub>	200	mA
Power Dissipation	PD	400	mW
Thermal Resistance, Junction to Ambien	$\theta_{JA}$	70	°C/W
Operating Temperature Range	T <sub>OPR</sub>	-40 ~ 125	°C
Storage Temperature Range	T <sub>STG</sub>	-65 ~ 150	°C

**Absolute Maximum Ratings** (Unless otherwise noted,  $T_A = 25 \text{ °C}$ )

#### **Electrical Characteristics** (Unless otherwise noted, $T_A = 25^{\circ}C$ , $V_{DD} = 3V$ )

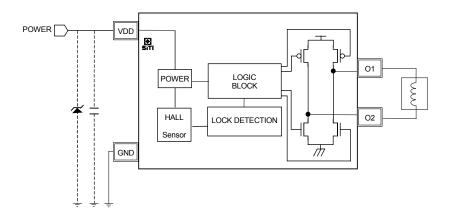
Characteristic	Sym.	Condition	Limit			Unit	
			Min.	Тур.	Max.		
Supply Voltage	$V_{DD}$	Operating	1.8	3	4.5	V	
Magnetic Specifications ( $T_J = 25^{\circ}C$ )							
Operating Point	B <sub>OP</sub>		-	1.0	10	тт	
Release Point	B <sub>RP</sub>		-	-1.0	-10	mT	
Hystersis	B <sub>HYS</sub>		-	2.0	20	mT	
O1/O2 Output Terminal ( $T_J = 25^{\circ}C$ )							
Output Voltage High	V <sub>OH</sub>	I <sub>OUT</sub> = 100 mA	2.6	2.85	-	V	
Output Voltage Low	V <sub>OL</sub>	I <sub>OUT</sub> = 100 mA	-	0.3	0.5	V	
Output Current	I <sub>OUT</sub>	<b>R</b> <sub>L</sub> = 30 Ω	-	85	-	mA	
Automatic Self-Restart Circuit							
On Time	T <sub>ON</sub>	-	-	156	-	ms	
Duty Ratio	$R_{DR}$	T <sub>OFF</sub> / T <sub>ON</sub>		3			

### Driver Output v.s. Magnetic Pole

Magnetic Field	01	02
North magnetic pole	Н	L
South magnetic pole	L	Н



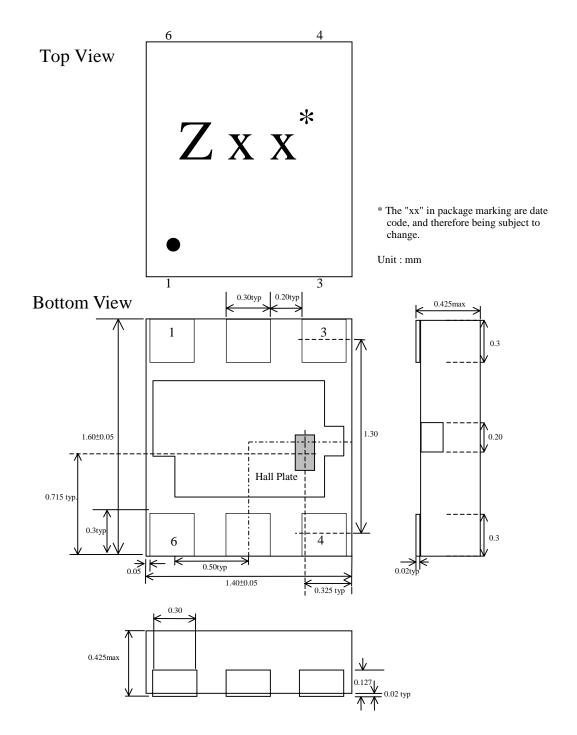
### **Block Diagram & Application Circuit**



#### **Application Notes**

□ The connection of the capacitor or Zener Diode between VDD and GND will increase stability of operation, if required.

## Package Specifications (CSP6)



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